

Groups of Polynomial Growth Learning Seminar

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Mondays 1:30 pm - 2:30 pm

Outline

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|----------------------|---|------------------|
| I) Setting | } | General Overview |
| II) Key Features | | |
| III) Some Results | | |
| IV) Basic Lie Theory | } | Some Prereq. |
| V) Geometry | | |
| VI) Structure Theory | } | The meat. |

Appendix

- i) Questions
- ii) Explicit Examples
- iii) Bib.

Main Ref: Analysis on Lie Groups with Polynomial Growth

Duney, de Elst, Robinson

* Groups are always connected and often simply connected.

I) Setting

$$(G, \Sigma, d\mu, d)$$

G = a Lie group

$\Sigma = \{X_1, \dots, X_m\}$ = a Hörmander basis

$d\mu$ = Haar measure

d_{cc} = Carnot - Carathéodory (cc) - metric induced by Σ .

Group of Polynomial Growth :

Let B_r = cc-metric ball centered at $e \in G$
of radius r

$|B_r|$ = $d\mu$ -volume of B_r

$\hookrightarrow G$ is a G.P.G. $\iff \exists D \in \mathbb{N}, c, C > 0$ s.t.
 $c r^D \leq |B_r| \leq C r^D, \quad r \geq 1.$

D does not depend on the choice of Σ (hence on $m = \#\Sigma$ nor d_{cc})

$\hookrightarrow D$ is intrinsic to G .

Examples:

- i) compact groups and nilpotent groups are $G \circ PG$.
- ii) Non-unimodular always have exponential growth
- iii) $PG \Rightarrow$ unimodular but unimodular $\nRightarrow PG$
- iv) Non-compact semi-simple Lie groups are unimodular but of exponential growth.
- v) Harmonic AN groups have exponential growth.

II) Key Features

- 1) Group action $G \curvearrowright G$ constrains volume growth
- 2) May study global properties of G using heat equation methods

$$L = \partial_t \rightarrow |h_t| \lesssim t^{-\frac{1}{2}} |B_{\sqrt{t}}|^{-1} e^{-|x|^2/4t}, \quad t > 0$$

sub Laplacian $\|h_t\|_{L^p} \lesssim t^{-\frac{1}{2}} |B_{\sqrt{t}}|^{-\frac{1}{p}}, \quad t > 0$

- 3) Natural setting to study complex coefficient invariant 2nd order subelliptic operators on G .

- 4) Rich structure theory:

$$G = M \ltimes Q, \quad Q \leadsto Q_N = \text{nilshadow}$$

$\text{cpt} \nearrow$ $\hat{\text{solvable}}$ $\hat{\text{nilpotent, diffeo. to } Q}$

• $G \leadsto$ "cylindrical manifold" $M \times Q_N$

- Heat equation analysis $\leadsto \mathbb{T}^d \times \mathbb{R}^m$

- H on $G \leadsto \hat{H}$ on Q_N

2nd order invariant
subelliptic

\hat{H} governs asymptotics
of H .

Uses homogenization
theory.

- K, \hat{K} semigroup kernels for H, \hat{H}

$$\hookrightarrow |K_t(mq) - \hat{K}_t(q)| \lesssim t^{-1/2} |B_{\sqrt{t}}|^{-1/2}$$

III) Some Results

Heat Kernel Estimates:

Proposition (Saloff-Coste, Varopoulos)

$G \hookrightarrow G \circ P_G$; $\bar{X} = \{X_1, \dots, X_m\}$ = Hörmander basis
 h_t = heat kernel of $L = \sum_{i=1}^m X_i^2 - \partial_t = 0$

$$|X_i \partial_t^k h_t(x)| \lesssim |B_{\sqrt{t}}|^{-1} t^{-k-1/2} e^{-\frac{|x|^2}{ct}}, (t, x) \in \mathbb{R}_{>0} \times G$$

$$h_t(x) \gtrsim |B_{\sqrt{t}}|^{-1} e^{-\frac{c|x|^2}{t}}, (t, x) \in \mathbb{R}_{>0} \times G$$

Sobolev Inequality

Theorem (Varopoulos)

$G \hookrightarrow G \circ P_G$

d = local dimension $|B_r| \sim r^d$ for $0 < r < 1$

D = dimension at ∞ $|B_r| \sim r^D$ for $1 < r < \infty$

$\alpha \in \mathbb{N}_{>0}$, $1 \leq p < \infty$, $n \in [d, D]$, $\alpha p < n$, $q = \frac{np}{n - \alpha p}$

$\hookrightarrow \|f\|_q \leq C \|f\|_{q, \alpha}$, $f \in C_0^\infty(G)$

$\|f\|_{p, 0} = \|f\|_p$, $\|f\|_{p, \alpha} = \sum_{i=1}^m \|X_i f\|_{p, \alpha-1}$

Note $\dim G \leq d$ but $d \leq D$ need not hold

Trudinger Inequality

Theorem (Sobolev-Coste)

G, d, D as above

$1 < p < \infty$, $\alpha p = d$ or $\alpha p = D$

$\hookrightarrow \exists c > 0$ s.t.

$$\int_{\Omega} \exp\left(\frac{|f(x)|^p}{c \|f\|_{p,\alpha}^p}\right) dx \leq c |\Omega|$$

$\forall f \in C_0^\infty(\Omega)$, $\Omega \subset G$ open.

Also harmonic analysis results on
multipliers + Riesz Transforms etc.

IV) Basic Lie Theory

G : a Lie Group

- The maps $(g, h) \mapsto gh$ and $g \mapsto g^{-1}$ are smooth

Often $G \cong \mathbb{R}^N$, (at least locally)
 $gh = (f_1(g, h), \dots, f_N(g, h))$

- A measure μ on G is called **left-invariant** on G provided
 $\mu(gA) = \mu(A) \quad \forall g \in G \text{ and measurable } A \subset G$
 - $gA = \{ga : a \in A\}$ = left translates of A .
- Right-invariant measure is similarly defined
- Every Lie group G has a canonical left-invariant measure called the **left Haar measure** μ_L satisfying
 - is a Borel measure
 - is left invariant
 - $K \subset G$ cpt $\rightarrow \mu_L(K) < \infty$
 - outer regular: $\mu_L(S) = \inf \{ \mu(U) : S \subset U, U \text{ open} \}$
 - inner regular: $\mu_L(U) = \sup \{ \mu(K) : K \subset U, K \text{ cpt} \}$

• The **right Haar measure** μ_R is similarly defined.

• μ_L and μ_R are unique up to scaling

• If $\mu_R = \mu_L$, then G is called **unimodular**

\mathfrak{g} : a (finite dimensional real) **Lie algebra**

• $\mathfrak{g} \cong \mathbb{R}^N$ and \mathfrak{g} has an alternating bilinear map

$$\mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}; (X, Y) \mapsto [X, Y]$$

(called a **Lie bracket**) which satisfies

• $[aX + bY, Z] = a[X, Z] + b[Y, Z]$

• $[X, aY + bZ] = a[X, Y] + b[X, Z]$

• $[X, X] = 0$ ($[X, Y] = -[Y, X]$)

• **Jacobson identity**:

$$[X, [Y, Z]] + [Z, [X, Y]] + [Y, [Z, X]] = 0$$

Exercise: $(\mathfrak{g}, [\cdot, \cdot])$ is associative iff it is 2-step nilpotent or abelian

Example

$sl(n, \mathbb{R}) = n \times n$ real matrices A w/ $\text{tr} A = 0$

and $[A, B] = AB - BA$, $A, B \in sl(n, \mathbb{R})$

Vector Fields :

On \mathbb{R}^M : $X = \sum_{j=1}^M a_j(x) \partial x_j$
First order differential operator.

$\mathcal{X}(\mathbb{R}^M) =$ Vector fields on \mathbb{R}^M

\hookrightarrow commutator is a Lie bracket :

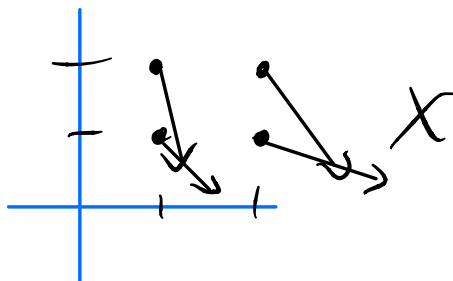
$$[X, Y]u = X(Yu) - Y(Xu)$$

$$X, Y \in \mathcal{X}(\mathbb{R}^M), u \in C^2(\mathbb{R}^M)$$

$\hookrightarrow (\mathcal{X}(\mathbb{R}^M), [\cdot, \cdot])$ is a Lie algebra.

Example : $X = x\partial_x - y\partial_y$ on \mathbb{R}^2

$$X \rightsquigarrow (x, -y)$$



On G : $X: G \rightarrow TG$, $g \mapsto v \in T_g G$

\hookrightarrow locally

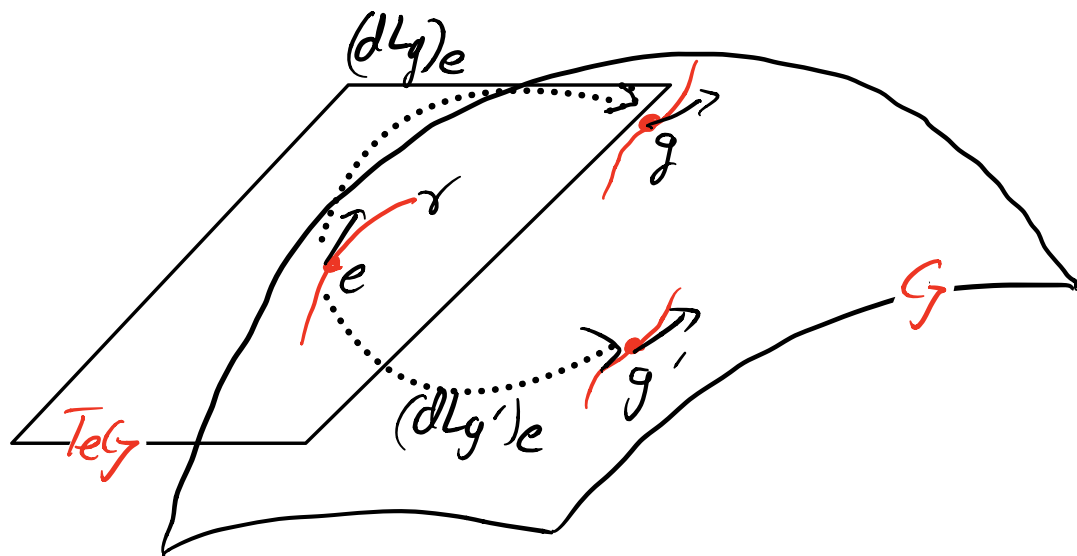
$$X = \sum_{j=1}^{\dim G} a_j(x) \partial x_j$$

$\mathcal{X}(G)$ = vector fields on G - also
a Lie algebra w/
 $[\cdot, \cdot]$ = commutator

- There are special v.f.s which respect the group structure on G .
- Let $L_g: G \rightarrow G$ denote left multiplication:
 $L_g(h) = gh$.
- A vector field X is called **left-invariant** if
$$(Xu)(g \cdot) = X(u(g \cdot)) \quad \forall g \in G$$
$$(Xu) \circ L_g = X(u \circ L_g)$$
- Let $\mathcal{X}_L(G)$ = space of left-invariant vector fields.
 - also a Lie algebra w/ $[\cdot, \cdot]$ = commutator

- Let $\mathfrak{g} \cong T_e G$
 - $\hookrightarrow v \in \mathfrak{g} \mapsto X_g = (dL_g)_e v \in T_g G$
 - $\hookrightarrow X \in \mathcal{X}_L(G), X: G \rightarrow TG$
 - $X_g u = (dL_g)_e v(u) = \left. \frac{d}{dt} \right|_{t=0} u \circ L_g \circ \gamma(t)$
 $\gamma(0) = e, \gamma'(0) = v \in T_e G$

- $v \mapsto X$ is a Lie Algebra isomorphism
 $\mathfrak{g} \rightarrow \mathcal{X}_L(G)$
- \mathfrak{g} is given the bracket
 $[v, w] \cong [X_v, X_w]_e$
 $v \mapsto X_v, w \mapsto X_w$



* Short hand: $\mathfrak{g} = \text{Lie } G \rightarrow \mathfrak{g}$ is the Lie algebra of G .

Key point: we may study \mathfrak{g} or $\mathcal{H}_L(G)$

Algebraic basis: A collection $a_1, \dots, a_d' \in \mathfrak{g}$
s.t. $\exists r \in \mathbb{N}$ s.t.
 a_1, \dots, a_d' and their brackets

$$[a_{i_1}, [a_{i_2}, \dots [a_{i_{n-1}}, a_{i_n}]]], \quad i_j \in \{1, \dots, d'\}$$

$n \leq r$

span \mathfrak{g} . The smallest r is called the **rank** of \mathfrak{g} with respect to a_1, \dots, a_d'

- In general: \mathfrak{g} may have multiple algebraic bases with different ranks.

Linear basis: usual linear algebra basis.

- $a_1, \dots, a_d' =$ algebraic basis, write
 $A_1, \dots, A_d' =$ corresponding left-invariant
vector fields.

$$(Ad)_g \cong \text{Ad} \circ L_g \circ Ad.$$

- We may call A_1, \dots, A_d' or a_1, \dots, a_d'
an algebraic basis.

Example: $H = \mathbb{R}^3$ with group law
 $(x, y, t)(a, b, s) = (x+a, y+b, t+s + \frac{1}{2}(ya - xb))$
 has left invariant vector fields

$$X = \partial_x + \frac{1}{2}y\partial_t, Y = \partial_y - \frac{1}{2}x\partial_t, T = \partial_t$$

which satisfy $[X, Y] = T$.

In particular, $X|_{(x,y,t)=e}, Y|_{(x,y,t)=e} \in T_e H$
 form an algebraic basis.

$H =$ Heisenberg Group \sim is a G.P.G.

Example: on \mathbb{R}^2 : $X = \partial_x, Y = x\partial_y$

$$[X, Y] = \partial_y$$

$\therefore X, Y, [X, Y]$ span \mathbb{R}^2 at
 each point

$\hookrightarrow X, Y$ not invariant under a Lie group
 product.

Sub-Laplacian:

On \mathbb{R}^N : $X_j = \partial x_j \implies \text{Laplacian} = \Delta = \sum_{j=1}^N X_j^2$

On G : $A_1, \dots, A_{d'}$ \implies sub-Laplacian $= L = \sum_{j=1}^{d'} A_j^2$

Note: L is not canonical in general

L is a 2nd order left-invariant differential operator

$$L(u \circ L_g) = (Lu) \circ L_g \quad \forall g \in G$$

- Play analogous role as Δ
- Common PDEs to study:

$$L = 0 \quad (\text{harmonic functions})$$

$$L = f \quad (\text{Poisson's Equation})$$

$$L = \partial_t \quad (\text{Heat Equation})$$

$$L = i\partial_t \quad (\text{Schrödinger's Equation})$$

- More generally:

On \mathbb{R}^N : consider operators

$$L = \sum_{i,j=1}^N a_{ij} \partial x_j \partial x_i, \quad a_{ij} \in \mathbb{R}$$

$$A = (a_{ij}), \quad A \geq \mu I$$

On G : $H = -\sum_{j,k=1}^{d'} c_{jk} A_j A_k, \quad c_{jk} \in \mathbb{C}$

$$\operatorname{Re}(c_{jk})_{j,k} \geq \mu I, \quad \mu > 0.$$

$\hookrightarrow H$ a \mathbb{C} -coefficient 2nd order left-invar. 2nd order operator.

V) Geometry

Length Metrics :

\mathcal{L} = a family of paths in \mathbb{R}^N . $\forall x, y \in \mathbb{R}^N$
 $\exists \mathcal{L} \ni \gamma: [0, 1] \rightarrow \mathbb{R}^N$ s.t. $\gamma(0) = x, \gamma(1) = y$
& one may only travel along these paths

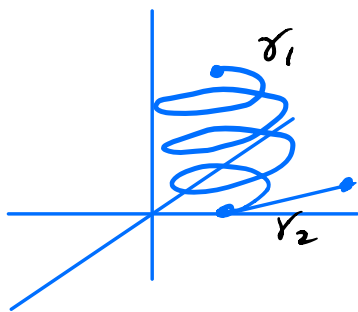
$$\text{Then } d_{\mathcal{L}}(x, y) \cong \inf_{\substack{\gamma \in \mathcal{L} \\ \gamma(0) = x \\ \gamma(1) = y}} \int_0^1 |\dot{\gamma}(t)| dt$$

= "length of shortest path connecting x to y "

measures distance according to this constraint.

↳ Specifying \mathcal{L} introduces a constrained non-Euclidean geometry on \mathbb{R}^N

Example



Vector field Defined Length Metric:

$G = \text{Lie group}$, $\mathfrak{g} = \text{Lie } G$

$a_1, \dots, a_d = \text{Linear basis for } \mathfrak{g}$

$\exists \gamma: [0, 1] \rightarrow G$, $\gamma(0) = g$, $\gamma(1) = h$, abs. cont.

and γ_k s.t. $\gamma'(t) = \sum_{k=1}^d \gamma_k(t) A_k|_{\gamma(t)}$ (a.e.)

The velocity vectors of γ are linear combinations of $\{A_k|_{\gamma(t)}\}$ for a.e. $t \in [0, 1]$.

↳ Define a distance

$$d(g, h) = \inf_{\substack{\gamma(0)=g \\ \gamma(1)=h}} \int_0^1 \left(\sum_{k=1}^d \gamma_k^2(t) \right)^{1/2} dt$$

= "length of shortest path $h \mapsto g$ "

Elliptic Modulus: $|g| \triangleq d(g, e)$

- d is left-invariant

- All elliptic moduli on G are equivalent:

$$c^{-1} | \cdot |_a \leq | \cdot |_b \leq c | \cdot |_a$$

(change of basis argument)

- Global and local geometry independent of linear basis.

Now consider $a_1, \dots, a_{d'}$ = algebraic basis

↳ can still define a distance (despite $d' \leq \dim G$)

Why? $A_1, \dots, A_{d'}$ satisfy Hörmander's condition (due to left translation):

$A_1|_g, \dots, A_{d'}|_g$ and their commutator of length $\leq r$ (= their rank) span $T_g G \forall g \in G$.

↳ $\forall g, h \in G \exists \gamma: [0, 1] \rightarrow G, g \mapsto h$, abs. cont. and $\dot{\gamma}_k$ s.t.

$$\dot{\gamma}'(t) = \sum_{k=1}^{d'} \dot{\gamma}_k(t) A_k|_{\gamma(t)} \quad (\text{a.e.})$$

Note: velocity of γ is constrained to $\text{span} \{A_k: k=1, \dots, d'\}$

Subelliptic distance:

$$d'(g, h) = \inf_{\substack{\gamma(0)=g \\ \gamma(1)=h}} \int_0^1 \left(\sum_{k=1}^{d'} \dot{\gamma}_k^2(t) \right)^{1/2} dt$$

a.k.a.: Carnot-Carathéodory metric or Control distance

Subelliptic modulus: $|g|' = d'(g, e)$

If $a_1, \dots, a_{d'} \rightsquigarrow d(\cdot, \cdot)$, $a_1, \dots, a_{d'}, \dots, a_d \rightsquigarrow d(\cdot, \cdot)$

↳ $d(\cdot, \cdot) \leq d'(\cdot, \cdot)$, $1 \cdot 1 \leq 1 \cdot 1'$

More paths for linear basis

Proposition $|\cdot|$ = subelliptic modulus for alg. basis of rank r ; $|\cdot|$ = elliptic modulus
 $\hookrightarrow \exists c > 0 : c^{-1}|g| \leq |g|' \leq c|g|^{1/r}, g \in G, |g| \leq 1.$

rank $r > 1 \rightarrow |\cdot|$ and $|\cdot|'$ not locally equivalent.

Proposition $|\cdot|, |\cdot|'$ as above.

$\hookrightarrow \exists \delta > 0, c > 0 : c^{-1}|g| \leq |g|' \leq c|g|, g \in G, |g| \geq \delta$

All moduli are equivalent outside a compact set.

Local Growth : Fix an algebraic basis a_1, \dots, a_d . $|\cdot|', d'(c, \cdot) =$ corresponding modulus and distance.

$B_p' = \{g \in G : |g|' < p\}, V'(p) \stackrel{\text{Haar measure}}{=} |B_p'| = \text{volume}$

Proposition $\exists D' \geq d = \dim G, C > 0, c > 0$ s.t.
 $c p^{D'} \leq V'(p) \leq C p^{D'}, p \in (0, 1).$

$D' =$ local dimension wrt a_1, \dots, a_d
 i.e.s.

Thm 3.14 ~

D' depends on basis and but there is a maximal local dimension.

Computing D' :

$$\mathfrak{g}_1' \triangleq \text{span}\{a_1, \dots, a_d\}$$

$$\mathfrak{g}_k' \triangleq \text{span}\{a_1, \dots, a_d, \text{commutators w/order } \leq k\}$$

$$\hookrightarrow \mathfrak{g}_1' \subset \mathfrak{g}_2' \subset \dots \subset \mathfrak{g}_r' = \mathfrak{g}$$

Set $\mathfrak{h}_1' = \mathfrak{g}_1'$, choose \mathfrak{h}_k' s.t. $\mathfrak{g}_k' = \mathfrak{h}_k' \oplus \mathfrak{g}_{k-1}'$

$$\hookrightarrow \mathfrak{g} = \mathfrak{h}_1' \oplus \dots \oplus \mathfrak{h}_r'$$

\hookrightarrow

$$D' = \sum_{k=1}^r k \dim \mathfrak{h}_k'$$

$$d = \sum_{k=1}^r \dim \mathfrak{h}_k'$$

locally Haar measure
in terms of Hausdorff
meas.

Global Growth:

Equivalence of \cdot, \cdot' away from $e \in \mathfrak{g}$

\hookrightarrow global Growth is intrinsic

\hookrightarrow Growth of $p \mapsto V(p)$ independent of basis.

Two Possibilities:

Dimension of ω .

1) $\exists D \in \mathbb{N}_{\geq 0}$ and $c, C > 0$ s.t.

$$c p^D \leq V(p) \leq C p^D \implies \text{Group of Polynomial Growth}$$

2) $\exists \lambda, \mu > 0, c, C > 0$ s.t.

$$c e^{\lambda p} \leq V(p) \leq C e^{\mu p} \implies \text{Group of exponential Growth}$$

Exercise: \S G_1, G_2 are connected groups.
 \S G_1 has polynomial growth and G_2 has exponential growth. Show that $G_1 \times G_2$ has exponential growth.

Proposition All nonunimodular groups are of exponential growth

Proof

Δ = modular function

$\Omega \mapsto \mu_L(\Omega g) \rightsquigarrow$ a left-Haar measure

$\hookrightarrow \exists \Delta: G \rightarrow \mathbb{R}_{>0}$ s.t. $\mu_L(\Omega g) = \Delta(g) \mu_L(\Omega)$

$\exists g \in B_1'$ s.t. $\Delta(g) > 1$.

$h \in B_1' \rightarrow hg^n \in B_{n+1}' \rightarrow B_1' g^n \subset B_{n+1}'$

Use $d(hg^{-1}, e) = d(h, g) \leq d(h, e) + d(e, g^{-1})$

$\hookrightarrow \mu_L(B_{n+1}') \geq \mu_L(B_1' g^n) = (\Delta(g))^n \mu_L(B_1')$

\hookrightarrow has exponential growth.

Proposition

G = simply connected and nilpotent
 $\dim G = d$

$\mathfrak{g} = \text{Lie } G$, $\{\mathfrak{g}_k\}$ = lower central series

$$\mathfrak{g} = \mathfrak{h}_1 \oplus \mathfrak{h}_2 \oplus \dots \oplus \mathfrak{h}_{r_0}, \quad \mathfrak{g}_k = \mathfrak{h}_k \oplus \mathfrak{g}_{k+1}.$$

$\hookrightarrow D = \sum_{k=1}^{\infty} k \dim \mathfrak{h}_k = \dim. \text{ at infinity}.$

$D \geq d$ and $D = d$; ff $G = \mathbb{R}^d$.

VII) The Nilshadow and Structure Theory

Assume G is simply connected by passing to its universal covering group.

In general: a $G \circ PG$ is not even homogeneous (i.e., no dilation structures).

Goal: Suitably approximate a $G \circ PG$ by one which is stratified.

Two paths:

① Nilshadow + contractions:

$$G = M \rtimes Q \cong_{\text{mfld}} G_N = M \times Q_N$$

M = Levi subgroup, cpt, sim. con.,

Q = radical = largest solvable subgroup
a $G \circ PG$, sim. con.

Q_N = nilshadow of Q
 $\cong_{\text{mfld}} Q$

a $G \circ PG$, nilpotent
grp law = modification of Q 's

Now use contractions of N.R.S. to approximate Q_N by a stratified grp.

② Group quotient + Nilshadow:

$\mathfrak{g} = \tilde{\mathfrak{g}}/H$, where $\tilde{\mathfrak{g}}$ is a larger grp, whose radical $\tilde{\mathfrak{Q}}$ has a stratified nilshadow.

$$\tilde{\mathfrak{g}} = \mathfrak{m} \rtimes \tilde{\mathfrak{Q}}$$

$\tilde{\mathfrak{Q}}_N$ is stratified

Structure Theory

\mathfrak{g} = real Lie algebra

Ideal: a subsp. $\mathfrak{i} \subset \mathfrak{g} : [\mathfrak{g}, \mathfrak{i}] \subset \mathfrak{i}$

Subalgebra: a subsp. $\mathfrak{h} \subset \mathfrak{g} : [\mathfrak{h}, \mathfrak{h}] \subset \mathfrak{h}$
i.e., \mathfrak{h} is a Lie algebra

Solvable: $\mathfrak{g}^{(1)} \triangleq \mathfrak{g}, \mathfrak{g}^{(k+1)} \triangleq [\mathfrak{g}^{(k)}, \mathfrak{g}^{(k)}]$
 $\{\mathfrak{g}^{(k)}\} \triangleq$ **Derived series**.

$\S \exists k \in \mathbb{N} : \mathfrak{g}^{(k)} = \{0\} \xrightarrow{\Delta} \mathfrak{g} \text{ is solvable}$

Radical: the unique solvable ideal $\mathfrak{q} \subset \mathfrak{g}$ containing every other solvable ideal.

Semisimple $\mathfrak{g} : \mathfrak{q} = \{0\}$
 $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{g}$

Nilpotent: $\mathfrak{g}_1 \triangleq \mathfrak{g}, \mathfrak{g}_{k+1} \triangleq [\mathfrak{g}, \mathfrak{g}_k]$
 $\{\mathfrak{g}_k\} =$ **lower central series**

$\S \exists r_0 \in \mathbb{N} : \mathfrak{g}_{r_0+1} = \{0\} \neq \mathfrak{g}_{r_0} \xrightarrow{\Delta} \mathfrak{g} \text{ is nilpotent}$

Graded: $\mathfrak{g} = \bigoplus_{k \geq 0} \mathfrak{h}_k$ w/ all but finitely many 0 and $[\mathfrak{h}_k, \mathfrak{h}_j] \subset \mathfrak{h}_{k+j}$.

Stratified: \mathfrak{g} graded and \mathfrak{h}_1 generates \mathfrak{g} ; i.e., \mathfrak{g} has an algebraic basis contained in \mathfrak{h}_1 .

Nilradical: the unique nilpotent ideal $\mathfrak{n} \subset \mathfrak{g}$ containing every other nilpotent ideal.

$$\mathfrak{n} \subset \mathfrak{g}, \mathfrak{n} = \text{nilradical}(\mathfrak{g})$$

Levi subalgebra: a semisimple subalgebra $\mathfrak{m} \subset \mathfrak{g} : \mathfrak{g} = \mathfrak{m} \oplus \mathfrak{q}$ as v. spaces

◦ always exist

◦ Every \mathfrak{g} decomposes into a solvable and semisimple part.

Adjoint representation:

$$\text{ad} : \mathfrak{g} \rightarrow \text{End}(\mathfrak{g})$$

$$\text{ad } X \triangleq [X, \cdot].$$

"Ado Thm"
 \mathfrak{g} matrix

$\hookrightarrow \mathfrak{q} = \text{nilpotent}$

ad surjective?

$$\text{ad } X(Y) = [X, Y]$$

$$X, Y \in \mathfrak{g}$$

Nilpotent map: $A: \mathfrak{g} \rightarrow \mathfrak{g}$. $\exists n \in \mathbb{N} : A^n = 0 \Rightarrow A$ nilpotent.

Semisimple map: $B: \mathfrak{g} \rightarrow \mathfrak{g}$ s.t. each B -invariant subspace V ($BV \subset V$) has a complementary B -invariant subspace W ($\mathfrak{g} = V \oplus W$).

Jordan decomposition:

$\forall a \in \mathfrak{g} \exists$ semisimple $S(a): \mathfrak{g} \rightarrow \mathfrak{g}$, nilpotent $N(a)$ s.t.

$$\text{ad } a = S(a) + N(a)$$

$$[S(a), N(a)] = 0.$$

Adjoint action decomposes into s.s. and n. parts.

Semidirect product:

$\mathfrak{g}, \mathfrak{h}$ Lie algebras

$$\tau: \mathfrak{h} \rightarrow \text{End}(\mathfrak{g}), \tau[a, b] = [\tau a, \tau b]$$

$$\hookrightarrow \mathfrak{g} \rtimes_{\tau} \mathfrak{h} \cong (\mathfrak{g} \oplus \mathfrak{h}, [\ , \]_{\tau})$$

$$[(a, b), (a', b')]_{\tau} \cong ([a, a']_{\mathfrak{g}} + \tau(b)a' - \tau(b')a, [b, b']_{\mathfrak{h}})$$

• Levi decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{q} \rightarrow \mathfrak{g} = \mathfrak{m} \rtimes \mathfrak{q}$.

On the group level

G a Lie group w/ $\mathfrak{g} = \text{Lie } G$.

Call G X iff \mathfrak{g} is X , where

$X \in \{\text{nilpotent, semisimple, etc}\}.$

Theorem G con., $\mathfrak{h} \subset \mathfrak{g}$ a subalg.
 $\hookrightarrow \exists!$ con. subgrp H w/ $\mathfrak{h} = \text{Lie}(H)$

Theorem G sim. con.

$$\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{q}, \quad \mathfrak{m} \xrightarrow{\sim} \mathcal{M}, \quad \mathfrak{q} \xrightarrow{\sim} \mathcal{Q}$$

$\hookrightarrow \mathcal{M}, \mathcal{Q}$ sim. con. and closed in G ,
 $\mathcal{M} \cap \mathcal{Q} = \{e\}$ and

$$G = \mathcal{M} \mathcal{Q}$$

$$G = \mathcal{M} \rtimes \mathcal{Q}.$$

$\mathcal{M} \cong$ **Levi subgrp**, $\mathcal{Q} =$ **radical**

$$\exists \varphi: \mathcal{Q} \rightarrow \text{Aut}(\mathcal{M})$$

$$(m, q)(m', q') = (m \varphi(q') m', qq')$$

$$(m q' m' (q')^{-1}, qq')$$

The Nilshadow

Nilshadow :

$$\mathfrak{g} = \text{Lie alg.}$$

$$\mathfrak{q} = \text{rad}(\mathfrak{g})$$

$$\mathfrak{n} = \text{nilrad}(\mathfrak{g})$$

$$S(a) = \text{s.s. part of } \text{ad } a \quad \text{by Jordan dec.}$$

Fix subsp. $\mathfrak{v} \subset \mathfrak{q}$ s.t.

$$\text{i) } \mathfrak{q} = \mathfrak{v} \oplus \mathfrak{n}$$

$$\text{ii) } S(\mathfrak{v})\mathfrak{v} = \{0\} \quad \text{Such a } \mathfrak{v} \text{ always exists}$$

Lastly, if $a \in \mathfrak{g} = \mathfrak{m} \oplus \mathfrak{v} \oplus \mathfrak{n}$, write $a_{\mathfrak{v}}$ for the component of a in \mathfrak{v} .

Lastly define the bracket

$$[a, b]_{\mathfrak{N}} = [a, b] - \underbrace{S(a_{\mathfrak{v}})b + S(b_{\mathfrak{v}})a}_{\text{subtract off the "s.s. part."}}$$

on \mathfrak{q} .

The Lie algebra $(\mathfrak{q}, [a, b]_{\mathfrak{N}})$ is called a nilshadow of \mathfrak{q} and denoted by $\mathfrak{q}_{\mathfrak{N}}$. It is nilpotent.

• $[\cdot, \cdot]_{\mathfrak{N}}$ extends to a bracket

$$[\cdot, \cdot]_{\mathfrak{N}}^s : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g} \Rightarrow \mathfrak{g}_{\mathfrak{N}}^s \triangleq (\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{N}}^s) = \text{semidirect shadow}$$

$$[\cdot, \cdot]_{\mathfrak{N}}^s|_{\mathfrak{m}} = [\cdot, \cdot]|_{\mathfrak{m}}, [\cdot, \cdot]_{\mathfrak{N}}^s|_{\mathfrak{q}} = [\cdot, \cdot]_{\mathfrak{N}}$$

$$[\cdot, \cdot]_{\mathfrak{N}}^s|_{\mathfrak{m} \times \mathfrak{q}} = [\cdot, \cdot]|_{\mathfrak{m} \times \mathfrak{q}}.$$

Inverting the Shadow

Goal: pass from $\mathfrak{g}_N = \mathfrak{m} \times \mathfrak{q}_N$ and $\mathfrak{g}_N = \mathfrak{M} \times \mathfrak{Q}_N$ back to $\mathfrak{g} = \mathfrak{m} \ltimes \mathfrak{q}$ and $\mathfrak{G} = \mathfrak{M} \ltimes \mathfrak{Q}$.

Shadow:

$\mathfrak{g}_N \triangleq \mathfrak{m} \times \mathfrak{q}_N$ = direct product of Lie algebras $(\mathfrak{m}, [\cdot, \cdot]_{\mathfrak{g}|\mathfrak{m}}), (\mathfrak{q}_N, [\cdot, \cdot]_N)$.

Twisted Lie Bracket: $\tau: \mathfrak{g} \rightarrow \text{End}(\mathfrak{g})$ a rep. on \mathfrak{g} s.t. $\tau(\tau(a)b) = 0$.

Then

$[a, b]_{\tau} \triangleq [a, b] + \tau(a)b - \tau(b)a$
defines a Lie bracket on \mathfrak{g} .
Write $\mathfrak{g}_{\tau} = (\mathfrak{g}, [\cdot, \cdot]_{\tau})$.

Theorem Choose \mathfrak{m} and \mathfrak{q} as before. Define the rep. $\sigma: \mathfrak{g}_N \rightarrow \text{End}(\mathfrak{g}_N)$ by

$$\sigma(m, q)(m', q') = (0, (\text{ad}_{\mathfrak{g}} m + S(q, \cdot))q')$$

$m \in \mathfrak{m}, q \in \mathfrak{q}$.

Then $[\cdot, \cdot]_{\tau} = [\cdot, \cdot]_{\mathfrak{g}}$ and so

$$\mathfrak{g} = \mathfrak{m} \ltimes \mathfrak{q} = (\mathfrak{m} \times \mathfrak{q}_N)_{\sigma} = (\mathfrak{g}_N)_{\sigma}$$

$\circ \mathfrak{g}$ is a twisted Lie algebra of its shadow

- σ "adds back" s.s. part which was removed to define $[\cdot, \cdot]_N$ on \mathfrak{g}_N .

Twisted Products:

$T: \mathfrak{g} \rightarrow \text{Aut}(\mathfrak{g})$, $*$ = grp law on \mathfrak{g}
 \hookrightarrow twisted product

$$g \tau^* h \triangleq (T(h^{-1})g) * h$$

τ^* is associative iff $T(T(g)h) = T(h)$

- $\mathfrak{g}_T = (\mathfrak{g}, \tau^*)$ is a Lie grp w/

$$e_{\mathfrak{g}_T} = e_{\mathfrak{g}}, \quad h^{(-1)\tau} = T(h)(h^{-1})$$

τ^* -inverse

Lie grp shadows:

Let $\mathfrak{g} = \mathfrak{v} \oplus \mathfrak{n}$ as before.

Let $\tau_{\mathfrak{g}}(a) \triangleq -s(a_{\mathfrak{v}})$ so that

$[\cdot, \cdot]_N^s = [\cdot, \cdot]_Z$ = bracket on \mathfrak{g}_N^s

- $\tau_{\mathfrak{g}}: \mathfrak{g} \rightarrow \text{End } \mathfrak{g}$ descends to a hom.

$$T_{\mathfrak{g}}: \mathfrak{g} \rightarrow \text{Aut}(\mathfrak{g})$$

$$T_{\mathfrak{g}}(\exp a) \exp b = \exp(e^{-s(a_{\mathfrak{v}})} b)$$

$$G_N^s \triangleq (G, T_G^*) = \text{semidirect shadow}$$

$$\text{Let } T_Q = T_G|_Q.$$

$$\hookrightarrow Q_N = (Q, T_Q^*) = \text{nil shadow}$$

Lastly $G_N = M \times Q_N$ (direct prod. of grps) is called the shadow of G .

• Just as $g \mapsto c_g$ was inverted by

$$g = (c_g)\sigma,$$

$G \mapsto G_N$ may be inverted.

• $\sigma: c_g \rightarrow \text{End}(c_g)$ descends to a hom.

$$S: G \rightarrow \text{Aut}(G).$$

Theorem

$$G = M \rtimes Q = (M \times Q_N, S^*)$$

i) Questions

1) G a Lie group with inner product $\langle \cdot, \cdot \rangle$ on $\mathfrak{g} = \text{Lie } G$

$$\hookrightarrow \langle\langle u, v \rangle\rangle = \langle (dL_{g^{-1}})_g u, (dL_{g^{-1}})_g v \rangle, \quad u, v \in T_g G$$

is a left-invariant Riemann metric on G .

Q: G a $G \circ P(G) \Leftrightarrow \langle\langle \cdot, \cdot \rangle\rangle$ a metric with polynomial growth?

$\Delta \langle\langle \cdot, \cdot \rangle\rangle$ relates to sub-Laplacians?

Guess: \mathcal{X} = algebraic basis w/ sub-Laplacian L - Declare \mathcal{X} orthonormal \rightarrow sub-Riemannian inner product $\langle\langle \cdot, \cdot \rangle\rangle \rightarrow L$ relates to $L \langle\langle \cdot, \cdot \rangle\rangle$?

2) What about the Schrödinger equation
$$L = i \partial_t$$

and the Schrödinger kernel.

G a $G \circ P(G) \Rightarrow G = M \times Q$, M cpt, Q $G \circ P(G)$.

\Rightarrow heat kernel behaves like that on $\mathbb{R}^m \times \mathbb{T}^d$.

\hookrightarrow says things about Schrödinger kernel?

3) What is the maximal local dimension of a given G .

4) Higher order Trudinger inequality?

5) Let G_1, \dots, G_N be G_0 PG with dimensions at infinity D_1, \dots, D_N . Q is the dimension at infinity of $G_1 \times \dots \times G_N$ $D_1 + \dots + D_N$?

ii) Explicit Examples

1) Let G be the universal covering of the group of Euclidean motions on the plane

↳ G is 3d, solvable and $G \cong P(G)$

↳ Every sub-Laplacian on $G \rightsquigarrow$ 2nd order operator on \mathbb{R}^3 w/ periodic coefficients.

• $\mathfrak{g} = \text{Lie } G \rightarrow \{X_1, X_2, X_3\}$ a basis w/
 $[X_1, X_2] = X_3, [X_1, X_3] = -X_2, [X_2, X_3] = 0$

• $G \cong \mathbb{R}^2 \rtimes_{\tau} \mathbb{R}, \tau: \mathbb{R} \rightarrow GL(\mathbb{R}^2),$

$x \mapsto \text{rot}_x = \text{ccw rot. by } x.$

2) Example of non-unimodular group:

Group of affine transformations on \mathbb{R} :

$$G = \{x \mapsto ax+b : a \in \mathbb{R} \setminus \{0\}, b \in \mathbb{R}\} = \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \right\}$$

$$d\mu_L = \frac{1}{a^2} da db, \quad d\mu_R = \frac{1}{|a|} da db.$$

Note G is solvable.

iii) Bib

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